



CIVL Paragliding and Hang-Gliding Committees

*Fédération
Aéronautique
Internationale*

CIVL GAP

Centralised Cross-Country Competition Scoring for Hang-Gliding and Paragliding

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Editor's note: Hang-gliding and paragliding are sports in which both men and women participate. Throughout this document the words "he", "him" or "his" are intended to apply equally to either sex unless it is specifically stated otherwise.

Revision	Author	Changes
1.1	Joerg Ewald	Correction of a number of typos

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1 Introduction

This document contains all definitions required to score centralised cross-country competitions for both hang-gliding and paragliding. Its main purpose is to serve as an addendum to sections 7A and 7B of the FAI sporting code. Additionally, it should serve as an educational tool for all parties involved in such competitions, as a reference for the implementation of scoring systems, as well as a basis for future improvements and modifications.

1.1 Scope

The document's scope is restricted to scoring of FAI Category 1 cross-country competitions for hang-gliding and paragliding: World and Continental championships in both sports. CIVL's rule setting targets these competitions exclusively, whereas organisers of FAI Category 2 competitions as well as non-sanctioned competitions are free to score their competitions however they like. Most of them do follow CIVL's lead, though, so this document should also cover the majority of Category 2 events as well.

1.2 Sources

The remainder of this document is based on:

- "The GAP Guide" (2011 edition)
- FAI Sporting Code Section 7A for Hang-Gliding (2013 edition)
- FAI Sporting Code Section 7B for Paragliding (2013 edition)
- The scoring implementation within CIVL's scoring software, FS (aka "FScomp")
- Appendix C of the Paragliding World Cup Association's 2013 Competition Rules

1.3 Changes from previous edition

Changes from the 2012 edition of this document will be marked with a vertical sidebar.

1.4 Differences between Hang-Gliding and Paragliding

Initially, both hang-gliding and paragliding competitions used the same system for scoring, generally known as "GAP". But over time, through their two separate sporting codes, the two disciplines introduced more and more changes that would only apply to one, but not the other. This mainly in non-standard situations such as stopped tasks, pilots landing just short of goal, or pilots crossing the start line too early. Where not explicitly stated otherwise, the contents of this document always apply to both disciplines. Definitions applying only to one, but not the other, are clearly marked as such.

 Text marked in blue applies exclusively to hang-gliding.

 Text marked in orange applies exclusively to paragliding.

2 The GAP Philosophy

CIVL's scoring system is generally known as "GAP", named after the first-name initials of its three inventors Gerolf Heinrichs (G), Angelo Crapanzano (A) and Paul Mollison (P). Their intention was to "create a fair scoring system easily adaptable to any competition anywhere in the world, both for hang gliding and paragliding, with a philosophy that is easy for the pilot to understand, regardless of the mathematical complexity of the underlying formulas".

2.1 History

Work on GAP started in 1998, and it was officially introduced in 2000, to allow scoring of competitions based on GPS track logs, instead of photographic evidence as it had been used until then.

In 2002, an updated version, named "GAP 2002" was published. This introduced the concept of leading points, which are calculated by comparing the complete track logs of all pilots in a task. Leading points replaced the departure points used in GAP 2000

In 2005, a variation of GAP 2002 was introduced in Australia, named "OzGAP" or "OzGAP 2005". The difference to GAP lies mainly in the way arrival points are calculated, but this was never adopted by CIVL.

In 2008, "GAP 2008" was officially released. The main scoring mechanisms remained unchanged from the 2002 edition, but the implementation of GAP 2008 included several rules introduced in the sporting codes for either hang-gliding or paragliding. These cover stopped tasks, starting too early, and landing between the end of the speed section and goal.

In 2011, "GAP 2011" marked another software release where the main scoring remained unchanged from the 2002 definition and implementation. The main changes were all for paragliding: altitude bonus in stopped tasks, as well as a reduced number of available points in stopped tasks and in tasks with no pilots in goal.

In 2012, the "Jump the Gun" rule for early starts in hang-gliding competitions changed in S7A. This was implemented in FS, but this was also released, unfortunately, as "GAP 2011".

The 2014 edition presented here introduces a number of significant changes for paragliding, a few of which also apply to hang gliding. The majority of those changes originate from the Paragliding World Cup Association (PWCA), and 2014 will be the first time that both CIVL and PWCA score their paragliding competitions using the same formula. The changes are:

- Nominal launch parameter, see 5.1 (hang gliding and paragliding)
- Final glide decelerator, see 5.6 (paragliding)
- Goal shape, see 6.3 (paragliding)
- Purely linear distance points, see 11.1 (paragliding)
- Adjusted formula for leading points, see 11.3 (paragliding)
- No more arrival points, see 11.4 (paragliding)
- Scoring of stopped tasks, see 12.3 (hang gliding and paragliding)
- Use of FTV for competition scoring, see 14.1 (paragliding)

2.2 Scoring Process

Scoring follows a nine-step process, as depicted in Figure 1:

1. Setting the competition parameters, or “GAP parameters”, according to the competition site, the expected pilot level and the expected tasks. This happens once for each competition, at the outset, and must not be changed throughout the competition. See section 4.
2. Setting a task – this happens typically once per day on flyable days. See section 6.
3. Letting the pilots fly the task. See section 7.
4. Evaluating the task, by collecting all pilots’ track logs for this task, and determining for each pilot the distance flown and, if the end of speed section was reached, in what time this happened. See section 8.
5. Calculating the task validity based on the task’s statistical values such as fastest time to ESS, number of pilots in goal, average distance flown and several others. See section 9.
6. Points allocation: Calculating the maximum number of points awarded for distance, speed, leading and arrival, based on the task validity and the statistical values found in the task evaluation. See section 10.
7. Scoring each pilot’s flight, by calculating the awarded points for distance, speed, leading and arrival. The outcome, the pilots’ total score, is the sum of these four values. See sections 11 and 12.
8. Ranking all pilots according to their total score for the task results. See section 13.
9. Aggregation of task results for competition scoring and ranking. See section 14.

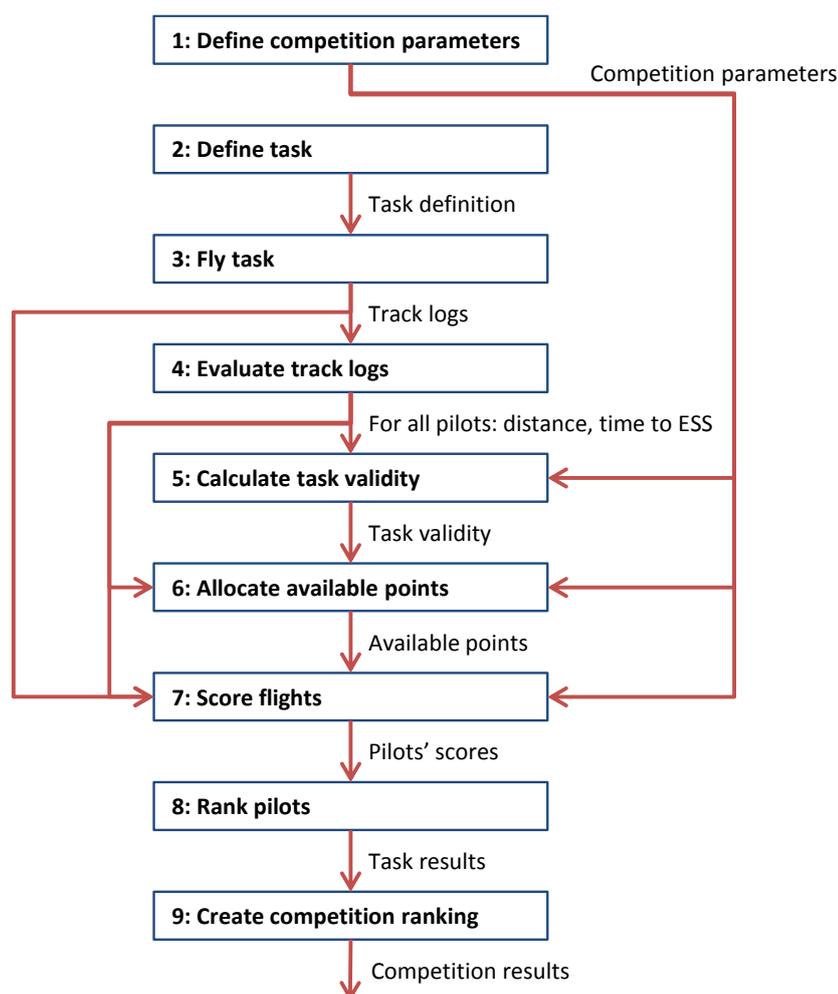


Figure 1: Scoring process

3 Definitions

The term “hang glider”, in this section, covers all classes. These definitions take precedence over the ones given in the General Section.

3.1 Flights

Flight: A flight of a hang glider, starting at take-off, and ending with the landing

Free flight: The part of a flight in which the hang glider is not towed, carried or assisted by another aircraft or separate external or jettisonable power source.

Flight performance: The achievement attained during free flight.

Competition task (short “task”): See section 6.1

Competition flight: A flight in a competition in which a pilot attempts to achieve a task as designed by the competition’s task committee.

3.2 Locations and distances

Take-off: Place where pilots launch for the task.

Speed section: A timed section of the task where speed points are awarded. The pilots that complete the speed section fastest receive the most time points.

Start of speed section (SSS): The location where timing of the task starts. In a task definition, this is either an exit or an entry cylinder. For an individual pilot, it’s the place where he crossed that cylinder to begin flying the speed section.

Turnpoint (TP): A turnpoint is a geographical point, defined by coordinates and altitude above mean sea level.

Control zone: A geographical area which must be reached by the pilots in the course of a competition task.

End of speed section (ESS): The cylinder/line/point where timing of the task stops.

Goal: The finish line or cylinder defining the task’s end. Can be identical to ESS, but is often chosen as a line or a smaller cylinder inside or even away from an ESS cylinder for safety reasons.

Landing place: The point where any part of the hang glider or its crew first touches the ground.

Task distance: The shortest possible distance a pilot has to fly to finish the task. This means he has to fly to the boundary of each cylinder, not the turnpoints at the cylinders’ centres.

Flown distance: A pilot’s individual achieved distance in a task.

Finish point: Either the landing place or the goal crossing point.

3.3 Times

Race start: The time when pilots are allowed to cross SSS and begin flying the speed section. In a race to goal task with a single start gate, this is also the start time for all pilots.

Start time: Time when a pilot starts flying the speed section.

Start gate: A timing reference for SSS. Depending on the chosen start procedure, multiple Start Gates can be available, offering pilots a choice of different race start times.

Window open time: The time from when pilots are allowed to launch.

Task deadline: The time until which pilots' flights are being scored. All distance covered after this time will not be counted for scoring.

Finish time: Time when a pilot crossed the ESS boundary in the required direction (exit or entry) for the first time after completing all previous portions of the task.

Task time: Time a pilot took to fly the speed section.

Landing time: The time at which any part of the hang glider or its crew first touched the ground.

4 Use of Tracklog Data

4.1 Position

Coordinates of positions, such as turn points or pilot positions, are always given as WGS84 coordinates, based on the WGS84 ellipsoid. The coordinate format is UTM by default, but other formats can be chosen by organisers as appropriate.

4.2 Distance

In general, task evaluation occurs in the x/y plain, therefore distance measurements are always exclusively horizontal measurements. The earth model used is the FAI sphere, with a radius of 6371.0 km.

✎ In paragliding, for final glide decelerators (5.6) and altitude bonus in stopped tasks (12.3.6), altitude is also considered, but this does not affect distance calculations between two geographic points.

✎ In hang gliding, for altitude bonus in stopped tasks (12.3.6), altitude is also considered, but this does not affect distance calculations between two geographic points.

The distance between two points, identified by their radian coordinates lat1/long1 and lat2/long2, is calculated using the Haversine formula.

$$\text{distLat} = \text{lat2} - \text{lat1}$$

$$\text{distLong} = \text{long2} - \text{long1}$$

$$a = \left(\sin \frac{\text{distLat}}{2}\right)^2 + \cos \text{lat1} * \cos \text{lat2} * \left(\sin \frac{\text{distLong}}{2}\right)^2$$

$$\text{radianDistance} = 2 * \arctan 2(\sqrt{a}, \sqrt{1-a})$$

$$\text{distance} = \text{radianDistance} * 6371000$$

To reproduce this formula in Excel, the following modification is necessary due to a different implementation of the arctan2 function:

$$\text{radianDistance} = \pi - 2 * \arctan 2(\sqrt{a}, \sqrt{1-a})$$

4.2.1 New distance measurement

Starting January 1st, 2015, all distance measurements and horizontal airspace validations are based on the WGS84 ellipsoid¹. From then on, it is each pilot's responsibility to either use an instrument that indicates distances to relevant features (such as turn points or airspace boundaries) based on the same earth model, or to adjust their flying to compensate for the differences in distance calculations between different earth models. Distance between two points is calculated using the Vincenty² formula. Planar projections, such as for example a localised Transverse Mercator³ projection with a scale factor <1, achieve sufficient accuracy for all practical purposes, where calculation performance is

¹ See http://en.wikipedia.org/wiki/World_Geodetic_System#A_new_World_Geodetic_System:_WGS_84

² See http://en.wikipedia.org/wiki/Vincenty%27s_formulae

³ See http://en.wikipedia.org/wiki/Transverse_Mercator_projection

a concern (for example in flight instruments), or where no formula exists to solve a problem on the ellipsoid (for example distance between point and line, as used for airspace evaluation).

The January 1st, 2015 deadline can be moved by the CIVL Bureau to a later date if a survey amongst instrument and software manufacturers shows that the main manufacturers have not yet managed to modify their software to measure distance based on the WGS84 ellipsoid.

4.3 Altitude

Altitude evaluation is based on GPS altitude, as given in GPS tracklogs.

4.3.1 New altitude measurement

Starting January 1st, 2015, altitude evaluation is based both on GPS and barometric altitude, as given in GPS tracklogs. Only GPS tracks where GPS altitude is given in reference to the Geoid⁴, as delivered by all commercial GPS modules, will be accepted in CIVL's FAI Category 1 events.

By default, in CIVL's FAI Category 1 events, the altitude values used in final glide decelerators and to determine altitude bonus in stopped task are calculated from a combination of GPS and barometric altitude, using the Dimov⁵ True Altitude algorithm. To score tasks taking into account the calculated true altitude values, a score keeper must either pre-process the raw tracklog files with the software published by Daniel Dimov, or, if supported by the scoring software, use the built-in functionality of the scoring software to the same effect.

Organisers may choose to use the less accurate pure GPS altitude instead.

Airspace violation checks rely exclusively on GPS altitude for the time being.

4.4 Time

Time evaluation is based on GPS time, as given in GPS tracklogs. For better readability, times of the day may be expressed in local time for the competition location.

⁴ See <http://en.wikipedia.org/wiki/Geoid>

⁵ See <http://fs.fai.org/wp-content/uploads/2013/03/True-Altitude-calculations.pdf>. Note that a real-time version of the algorithm discussed in this paper is currently under development. This version will be enable instrument manufacturers to display True Altitude in flight.

5 Competition Parameters

Before the first task, the following parameters must be defined by the meet director, or another person or group as defined by the competition's local regulations:

1. Nominal Launch
2. Nominal Distance
3. Minimum Distance
4. Nominal Goal
5. Nominal Time

The values set for these parameters define how each task's validity is calculated. They should therefore be chosen very carefully, considering the realistic potential of the flying site. Setting the values too low will prevent the formula from distinguishing between demanding, high quality tasks and quick, easy low quality tasks which are sometimes the only option due to weather conditions.

In paragliding competitions, the following must also be defined by the same person or group who defines the first five competition parameters above:

6. Final glide decelerator
7. Score-back time for stopped task

5.1 *Nominal Launch*

When pilots do not take off for safety reasons, to avoid difficult launch conditions or bad conditions in the air, Launch Validity is reduced (see section 9.1). Nominal Launch defines a threshold as a percentage of the pilots in a competition. Launch Validity is only reduced if fewer pilots than defined by that threshold decide to launch.

The recommended default value for Nominal Launch is 96%, which means that Launch Validity will only be reduced if fewer than 96% of the pilots present at launch chose to launch.

5.2 *Nominal Distance*

Nominal distance should be set to the expected average task distance for the competition. Depending on the other competition parameters and the distances actually flown by pilots, tasks shorter than Nominal Distance will be devalued in most cases. Tasks longer than nominal distance will usually not be devalued, as long as the pilots fly most of the distance.

In order for GAP to be able to distinguish between good and not-so-good tasks, and devalue the latter, it is important to set nominal distance high enough⁶.

5.3 *Minimum Distance*

The minimum distance awarded to every pilot who takes off. It is the distance below which it is pointless to measure a pilot's performance. The minimum distance parameter is set so that pilots who

⁶ See also this excellent series of articles on the subject: Part 1: <http://ozreport.com/1360767307>; Part 2: <http://ozreport.com/1360858575>; Part 3: <http://ozreport.com/1360944246>

are about to "bomb out" will not be tempted to fly into the next field to get past a group of pilots – they all receive the same amount of points anyway.

5.4 *Nominal Goal*

The percentage of pilots the meet director would wish to have in goal in a well-chosen task. This is typically 20 to 40%. This parameter has a very marginal effect on distance validity (see section 9.2).

5.5 *Nominal Time*

Nominal time indicates the expected task duration, the amount of time required to fly the speed section. If the fastest pilot's time is below nominal time, the task will be devalued. There is no devaluation if the fastest pilot's time is above nominal time.

Nominal time should be set to the expected "normal" task duration for the competition site, and nominal distance / nominal time should be a bit higher than typical average speeds for the area.

5.6 *Final Glide Decelerator*

The concept of a final glide decelerator was introduced to counteract a development in competition paraglider design which favoured stability at high speeds over stability at trim speed. The two final glide decelerators available are:

- Conical end of speed section (CESS): Instead of a cylinder, the end of speed section is an inverted cone. Time stops for a pilot when they enter that cone. For details see 6.2.2.
- Arrival altitude time bonus (AATB): The time bonus is calculated based on each pilot's altitude above goal when crossing the end of speed section cylinder. This bonus is then deducted from the pilot's speed section time to determine the score time. See also 8.5.

For safety reasons, a meet director may decide to not use any final glide decelerator for an individual task. This must be announced at the task briefing, and a specific reason must be given, indicating what exact risk is being averted by not using the final glide decelerator chosen for that competition.

5.7 *Score-back Time*

In a stopped task, this value defines the amount of time before the task stop was announced that will not be considered for scoring. The default is 5 minutes, but depending on local meteorological circumstances, it may be set to a longer period for a whole competition. See also section 12.3.1.

6 Task Setting

6.1 Definition of a task

A task can either be a race task or an open distance task.

6.1.1 Race task

A race task definition consists of:

1. A launch point, given as GPS coordinates
2. A number of control zones
3. A goal
4. An indication which of the control zones is the start (start of speed section)
5. If goal does not serve as end of speed section: An indication which of the control zones is the end of speed section, along with its specific parameters (such as incline and radius for CESS, altitude time bonus factor for AATB)
6. A launch time window
7. A start procedure, including timing
8. Optionally, a task deadline

In exceptional circumstances, with regard to restricted launch areas and poor flying conditions, to ensure the task is fair for 2/3rds of the pilots, a task may be run without leading/departure points. This is to be declared at the task briefing.

6.1.2 Open distance task

An open distance task definition consists of:

1. A launch point, given as GPS coordinates
2. A number of control zones
3. Optionally, an indication which of the control zones is the start
4. Optionally, a direction for the final, open distance leg
5. A launch time window
6. If a start control zone exists: A start time
7. A task deadline

6.2 Definition of control zones

Control zones are geographical areas which must be reached by the pilots in the course of a task.

The only control zone type is the turnpoint cylinder.

The three types of control zones are the turnpoint cylinder, the conical end of speed section and the goal semi-circle.

6.2.1 Definition of a turnpoint cylinder

A turnpoint cylinder is defined as:

1. A centre point c , given as GPS coordinates
2. A radius r , given in meters
3. An indication whether the cylinder is an “exit” or an “enter” cylinder. This defines whether the corresponding turnpoint is considered reached by a pilot when crossing the cylinder’s boundary from its inside to the outside, or from its outside to the inside.

A turnpoint cylinder is then given as the cylinder with radius r around the axis which cuts the x/y plain orthogonally at the cylinder’s centre point c . For task evaluation purposes, only the cylinder’s projection in the x/y plain is considered: a circle of radius r around c .

Note that for start cylinders (SSS), “enter” only makes sense if the following turnpoint cylinder lies within the SSS cylinder. Likewise, an “exit” only makes sense if the first turnpoint lies outside of the SSS cylinder. Currently, the start direction cannot be set within FS. Instead the program automatically scores according to this logic.

6.2.2 Definition of conical end of speed section

A conical end of speed section is defined as:

1. A centre point c , given as GPS coordinates and altitude
2. An incline i , given as a ratio of altitude/distance to the centre point
3. A radius r , indicating the size of the circle resulting from the intersection between the cone and a horizontal plane at goal altitude

A conical end of speed section is given as the cone resulting from an axis of inclination i through the centre point c' , which is equal to point c , but has its altitude lowered by r/i metres compared to c .

The incline is chosen for each task. The default value is 1:3.5. Values suggested for use are between 1:2.5 and 1:4.

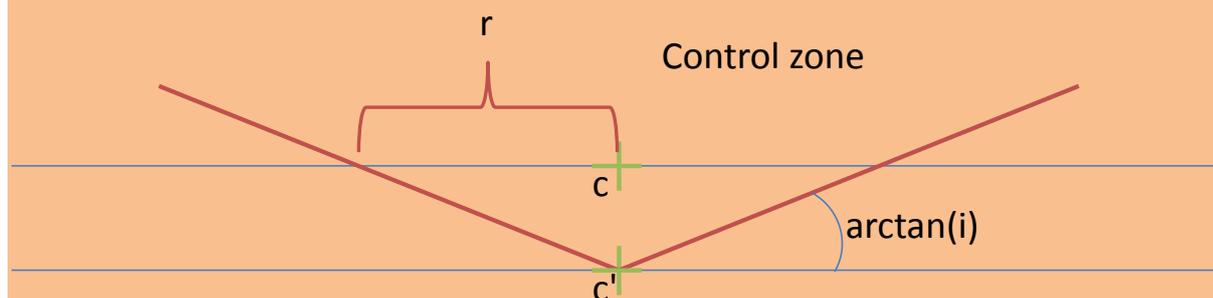


Figure 2: Conical end of speed section from the side

6.3 Definition of goal

A goal can be

1. A cylinder (enter or exit), see above, or
2. A line, defined by:
 - a. A centre point c , given as GPS coordinates
 - b. A length l , given in meters

- ⤿ If CESS is used, goal must be either a line at the cone's centre point, a cylinder at the cone's centre point with a radius smaller than radius r of the cone definition, or be located at a point that is different from the cone's centre point.

6.3.1 Goal line

A goal line is defined as a band of x/y width l through the centre point, which is cut orthogonally by the x/y projection of the connecting line between the centre of the last cylinder before goal with a different centre point than goal, and the goal line's centre point. For task evaluation purposes, only the band's projection in the x/y plain is considered: a line through the centre point c which is perpendicular to the connecting line between the centre of the last cylinder before goal with a different centre point than goal (P), and the goal line's centre point c , and which extends for $l/2$ into both directions from the centre point. See Figure 3.

Goal lines must be crossed in the direction of flight when coming from the last cylinder before goal with a different centre point than goal.

- ⤿ The goal control zone consists of the semi-circle with radius $l/2$ behind the goal line, when coming from the last turn point that is different from the goal line centre. Entering that zone without prior crossing of the goal line is equivalent to crossing the goal line.

Physical lines can be used in addition to the official, virtual goal line as defined by GPS coordinates, to increase attractiveness for spectators and media, and to increase visibility for pilots. Physical lines must be at least 50m long and 1m wide, made of white material and securely attached to the ground. The physical line must match as closely as possible the corresponding virtual line as defined by the goal GPS coordinates and the direction of the last task leg. It must not be laid out further from the previous turn point than the goal GPS coordinates.

By default, the goal line length l is set to 400m.

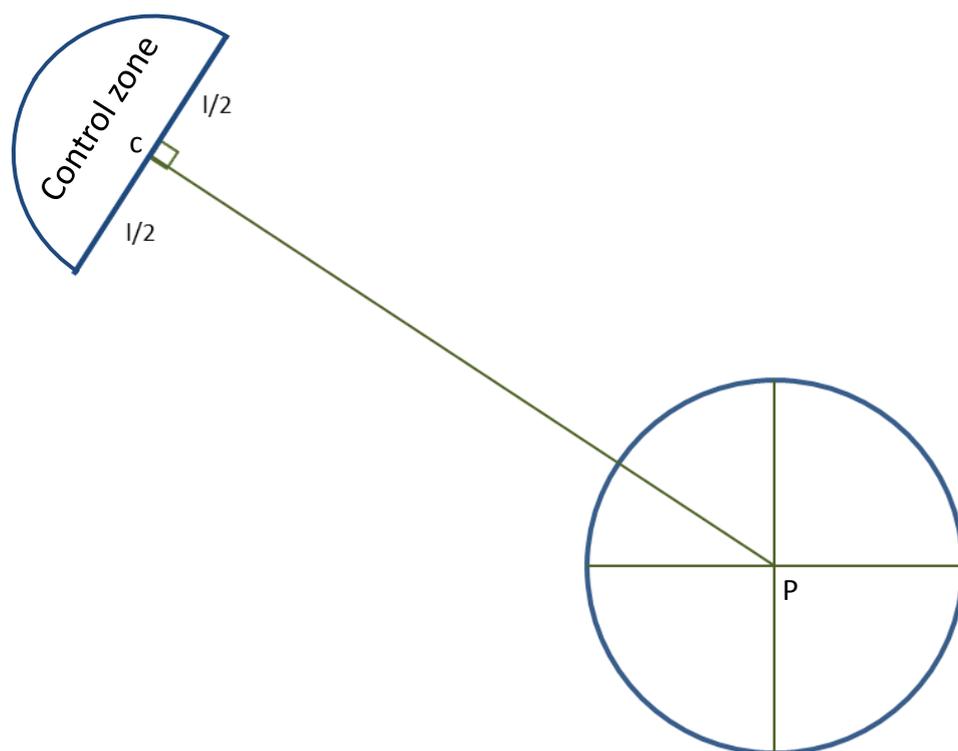


Figure 3: Goal line definition

6.4 Start procedures

Start procedures define how an individual pilot's start time is determined. A start can be either air- or ground-started, and it can be either a race to goal or an elapsed time start.

6.4.1 Air start

For air-started tasks, the competitors are free to launch any time during the launch window, and to fly about, regardless of any turnpoint or start cylinders, up to their race start. Race start is defined as the crossing of the start cylinder in the prescribed direction for the last time before continuing to flying through the remainder of the task.

6.4.2 Ground start

In a ground-started task, the race starts with the pilots' launch. Since a launch can be difficult to detect from a GPS track, the task setters must set a cylinder around the launch area as the first turnpoint. A pilot's start is registered when he exits this cylinder for the first time. In the case of a race to goal task, the launch window open time is the same as the first (or only) start gate time.

6.4.3 Race to goal

A race to goal start is defined by one or more so-called "start gates". The first – or only – start gate is given as a daytime. Subsequent start gates are given as a time interval, along with the number of start gates.

Example 1: "We have a Race to Goal task, the start gate opens at 13:00"

Example 2: “We have a Race to Goal task with 5 start gates from 13:30 at a 20 minutes interval.” – the start gate times in this case are 13:30, 13:50, 14:10, 14:30, and 14:50.

Pilots are free to start any time after the first (or single) start gate. A pilot’s start time is then defined as the time of the last start gate after which he started flying the speed section of the task.

Example 3: Given the start gates from Example 2 above, pilot A, crossing the start cylinder at 13:49:01, will be given a start time of 13:30. Any pilot starting after 14:50 will be given a start time of 14:50.

Starting before the first (or only) start gate is considered a failed start. Some refer to this as “jumping the gun”. The two disciplines handle failed starts differently, see section 12.2.

6.4.4 Elapsed time

An elapsed time start is defined by a single “start gate”, given as a daytime. Pilots are free to start any time after this start gate. A pilot’s start time is then defined as the time at which he started flying the speed section of the task. Each pilot has therefore an individual start time.

Example 1: “We have an Elapsed Time task, the start gate opens at 12:30” – pilot A starting at 12:31:03 has a start time of 12:31:03, pilot B starting at 15:48:28 has a start time of 15:48:28.

6.5 Distances

6.5.1 Task distance

Task distance is defined as the path of shortest distance from the start point to goal that touches all turnpoint cylinders. The method to calculate this distance is buried in FS’ code and will be documented at a later time.

Currently, this method mistreats the case where after ESS one or several turnpoints have to be reached with centres different from ESS’ centre point: The two legs to and from ESS are optimized for distance as well, which can result in a longer last leg before ESS than what pilots experience in reality. As a result, pilots can reach ESS with a shorter flown distance than what FS indicates is the distance required to reach ESS. This only affects pilots landing between ESS and goal, but does not represent a disadvantage to those pilots. The speed section distance calculation used for scoring (see below) is not affected by this.

6.5.2 Speed section distance

Speed section distance is defined as the path of shortest distance from start of speed section to end of speed section that touches all turnpoint cylinders. The method to calculate this distance is the same as for task distance.

7 Flying a task

7.1 Race task

Given a task definition, the pilots' task then consists of launching at the take-off point within the launch time window, reaching all given control zones in the given order and direction (enter or exit), including the start of speed section cylinder at a time permitted by the start procedure. A task is concluded by crossing the goal line in the direction from the last cylinder before goal with a different centre point than goal towards goal. In the absence of a goal line, the task conclusion is achieved by reaching the final turnpoint cylinder. If a task deadline is given, flights are only considered up to that time.

7.2 Open distance task

In open distance tasks, the pilot's task consists of launching from the take-off point within the launch time window, reaching all given control zones in the given order and direction (enter or exit), including, if one is defined, the start cylinder at or after the given start time, and then fly the maximum distance, either along a given direction, or in a free direction if none is given, away from the last given control zone. Flights are considered up to the task deadline.

8 Task evaluation

From each pilot's track, task evaluation determines the distance this pilot flew along the task, and the time this pilot took to fly the speed section.

8.1 Reaching a control zone

8.1.1 Reaching a turnpoint cylinder

A cylinder is considered "reached" by a pilot if that pilot's track log shows the pilot crossing out of the cylinder in the case of an exit cylinder, or into the cylinder in case of an enter cylinder, by containing at least one track point closer to the cylinder's centre than the cylinder radius (enter) or further away from the cylinder's centre than the cylinder radius (exit). During task evaluation, only the x/y coordinates are considered, and a point must lie within (enter) or outside of (exit) the circle representing the turnpoint cylinder in the x/y plain. This is determined by measuring the distance between a track point and the turnpoint. This distance must be greater (exit) or smaller (enter) than the cylinder's radius.

To compensate for different distance calculations and different earth models in use by today's GPS devices (FAI sphere vs. WGS84 ellipsoid), a 0.5% tolerance is used for this calculation. This had to be introduced so that a pilot reading the distance to the next cylinder centre from his GPS device can rely on having reached the turnpoint when the distance displayed by the instrument is smaller than the defined turnpoint cylinder radius.

For enter cylinders, this means that a tracklog point that is closer to the turnpoint than $r * 1.005$ is considered proof of reaching the turnpoint. For exit cylinders, this means that a tracklog point that is further away from the turnpoint than $r * 0.995$ is considered proof of reaching the turnpoint.

Starting January 1st, 2015 – provided all distance measurements are then based on the WGS84 ellipsoid (see 4.2) – the tolerance for turnpoint cylinders in CIVL's FAI Category 1 events will be reduced to 0.01% of the cylinder radius, with a minimum of 5 meter. Organisers of FAI Category 2 events may continue using the existing 0.5% tolerance, to accommodate pilots flying with instruments which calculate distance based on the FAI sphere.

The time when a control zone was reached is determined by the time a so-called "crossing" occurred. A crossing is defined as a pair of consecutive track points, of which at least one lies inside the band determined by the turnpoint's centre, its radius and the tolerance value.

$$tolerance = 0.5\% | 0.01\%$$

$$minTolerance = 0 | 5m$$

$$turnpoint_i : innerRadius_i = \min(radius_i * (1 - tolerance), radius_i - minTolerance)$$

$$turnpoint_i : outerRadius_i = \max(radius_i * (1 + tolerance), radius_i + minTolerance)$$

$$crossing_{turnpoint_i} : \exists j : (distance(center_i, trackpoint_j) \geq innerRadius_i$$

$$\wedge distance(center_i, trackpoint_{j+1}) \leq outerRadius_i)$$

$$\vee (distance(center_i, trackpoint_{j+1}) \geq innerRadius_i$$

$$\wedge distance(center_i, trackpoint_j) \leq outerRadius_i)$$

The time of a crossing depends on whether it actually cuts across the actual cylinder, or whether both points lie within the tolerance band, but on the same side of the actual cylinder.

$$\begin{aligned}
 &(\text{distance}(\text{center}_i, \text{trackpoint}_j) < \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) < \text{radius}_i) \\
 &\vee (\text{distance}(\text{center}_i, \text{trackpoint}_j) > \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) > \text{radius}_i) \\
 &\wedge \text{turnpoint}_i = \text{ESS} : \text{crossing.time} = \text{trackpoint}_{j+1}.\text{time}
 \end{aligned}$$

$$\begin{aligned}
 &(\text{distance}(\text{center}_i, \text{trackpoint}_j) < \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) < \text{radius}_i) \\
 &\vee (\text{distance}(\text{center}_i, \text{trackpoint}_j) > \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) > \text{radius}_i) \\
 &\wedge \text{turnpoint}_i \neq \text{ESS} : \text{crossing.time} = \text{trackpoint}_j.\text{time}
 \end{aligned}$$

$$\begin{aligned}
 &(\text{distance}(\text{center}_i, \text{trackpoint}_j) < \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) > \text{radius}_i) \\
 &\vee (\text{distance}(\text{center}_i, \text{trackpoint}_j) > \text{radius}_i \wedge \text{distance}(\text{center}_i, \text{trackpoint}_{j+1}) < \text{radius}_i) : \\
 &\text{crossing.time} = \text{interpolat eTime}(\text{trackpoint}_{j+1}, \text{trackpoint}_{j+1})
 \end{aligned}$$

The method used to interpolate the crossing time is buried in FS' code and will have to be documented at a later point.

Finally, given all n crossings for a turnpoint cylinder, sorted in ascending order by their crossing time, the time when the cylinder was reached is determined.

$$\begin{aligned}
 \text{turnpoint}_i = \text{SSS} : \text{reachingTime}_i &= \text{crossing}_n.\text{time} \\
 \text{turnpoint}_i \neq \text{SSS} : \text{reachingTime}_i &= \text{crossing}_0.\text{time}
 \end{aligned}$$

8.2 Reaching a conical end of speed section

A conical end of speed section is considered “reached” by a pilot if that pilot’s track log contains at least one point where the required glide angle to the cone’s centre point is equal to or smaller than the cone’s incline.

$$\text{crossing}_i : \exists j : \frac{\text{trackpoint}_j.\text{altitude} - \text{center}_{\text{CESS}}.\text{altitude}}{\text{distance}(\text{center}_{\text{CESS}}, \text{trackpoint}_j)} \leq \text{incline}$$

$$\wedge \frac{\text{trackpoint}_{j-1}.\text{altitude} - \text{center}_{\text{CESS}}.\text{altitude}}{\text{distance}(\text{center}_{\text{CESS}}, \text{trackpoint}_{j-1})} > \text{incline}$$

$$\text{crossing}_i.\text{time} = \text{interpolat eTime}(\text{trackpoint}_{j+1}, \text{trackpoint}_{j+1})$$

Given all n crossings for a CESS, sorted in ascending order by their crossing time, the time when CESS was reached is determined.

$$\text{reachingTime}_{\text{CESS}} = \text{crossing}_0.\text{time}$$

If goal is at the CESS centre point, and a pilot reaches goal without previously entering the CESS, he is considered having reached CESS at the time when he crossed the goal line.

8.3 Reaching goal

8.3.1 Goal cylinder

Verification of a pilot reaching a goal cylinder is achieved by the same method as verification of reaching a turnpoint cylinder (8.1.1)

8.3.2 Goal line

To reach goal in the case of a goal line, the goal line must be crossed in flight. This is achieved when a line drawn between two adjacent points in the pilot's tracklog crosses the goal line in the correct direction.

Entering the goal control zone (semi-circle behind the goal line, see 6.3.1) from any direction without prior crossing of the goal line is equivalent to crossing the goal line.

If a physical line is used, crossing either the virtual or the physical goal line counts as having reached goal. An official observation (through a goal marshal or similar) of a pilot crossing the line in flight overrules a negative goal crossing decision based on the pilot's tracklog. Not crossing a physical goal line for obvious safety reasons must be considered in the pilots' favour.

The physical goal line is crossed when the hang glider's nose cuts the line, in the correct direction, before a landing is made.

The physical goal line is crossed when the paraglider pilot's leading foot cuts the line, in the correct direction, before a landing is made.

8.4 Flown distance

8.4.1 Race task

To determine a pilot's flown distance, a first step determines which turnpoints he reached considering all timing restrictions: launch within launch time window, valid start, but only until the task deadline time. After the last turnpoint the pilot reached, for every remaining track point, the shortest distance to goal is calculated using the method described in section 6.5.1. The flown distance is then calculated as task distance minus the shortest distance the pilot still had to fly. Therefore, for scoring, the pilot's best distance along the course line is considered, regardless of where the pilot landed in the end.

If a pilot flies less than minimum distance, he will be scored for this minimum distance. This also applies to pilots who are not able to produce a valid GPS tracklog, but for whom launch officials verify launch within the launch window.

If a pilot reaches goal, he will be scored for the task distance.

$$\forall p: p \in \text{PilotsLandingBeforeGoal } \text{bestDistance}_p = \max(\text{minimumDistance}, \text{taskDistance} - \min(\forall \text{track}_p.\text{point}_i \text{ shortestDistanceToGoal}(\text{track}_p.\text{point}_i)))$$

$$\forall p: p \in \text{PilotsReachingGoal } \text{bestDistance}_p = \text{taskDistance}$$

8.4.2 Open distance task

In an open distance task, if a pilot lands before the last of any given control zones, his flown distance is calculated according to 8.4.1. For pilots flying further than the last control zone, the flown distance is calculated by adding the pilot's best distance flown in the open distance part of the task (after the last control zone) to task distance between launch and the last control zone. If the task gave a direction for the open distance leg, then the pilot's best distance projected onto that direction is considered.

8.5 Time for speed section

The time a pilot took to fly the speed section is determined by his start time (which is influenced by the task's start procedure and the time he crossed the start of speed section cylinder) and the time when he crossed the end of speed section after reaching all previous turn points. The smallest unit for time measurement is one second.

Pilots who do not reach the end of speed section cylinder do not get a time.

$$\forall p: p \in \text{PilotsReachingESS} : \text{time}_p = \text{timeAtESS}_p - \text{startTime}_p$$

If AATB is used, pilots receive a time bonus for their altitude above goal when crossing the ESS cylinder. The number of seconds they receive for each meter is expressed by the ATTB factor.

By default, the ATTB factor is 0.45 s/m. Values suggested for use are between 0.2 s/m and 0.7 s/m.

$$\forall p: p \in \text{PilotsReachingESS} :$$

$$\text{arrivalAltitudeTimeBonus}_p = (\text{crossing}_{p, \text{ESS}}.\text{altitude} - \text{goal}.\text{altitude}) * \text{ATTBfactor}$$

$$\text{time}_p = \text{timeAtESS}_p - \text{startTime}_p - \text{arrivalAltitudeTimeBonus}_p$$

9 Task Validity

The task validity is a value between 0 and 1 and measures how suitable a competition task is to evaluate pilots' skills. It is calculated for each task after the task has been flown, by multiplying the three validity coefficients: Launch validity, distance validity, and time validity.

$$\text{TaskValidity} = \text{LaunchValidity} * \text{DistanceValidity} * \text{TimeValidity}$$

9.1 Launch Validity

Launch validity depends on nominal launch and the percentage of pilots actually present at take-off who launched. If the percentage of pilots on take-off who launch is equal to nominal launch, or higher, then launch validity is 1. If, for example, only 20% of the pilots present at take-off launch, launch validity goes down to about 0.1.

The reasoning behind launch validity: Launch conditions may be dangerous, or otherwise unfavourable. If a significant number of pilots at launch think that the day is not worth the risk of launching, then the gung-ho pilots who did go will not get so many points. This is a safety mechanism.

'Pilots present' are pilots arriving on take-off, with their gear, with the intention of flying. For scoring purposes, 'Pilots present' are all pilots not in the 'Absent' status (ABS): Pilots who took off, plus pilots present who did not fly (DNF). DNFs need to be attributed carefully. A pilot who does not launch due to illness, for instance, is not a DNF, but an ABS.

$$LVR = \min\left(1, \frac{\text{NumberOfPilotsFlying}}{\text{NumberOfPilotsPresent} * \text{NominalLaunch}}\right)$$

$$\text{LaunchValidity} = 0.027 * LVR + 2.917 * LVR^2 - 1.944 * LVR^3$$

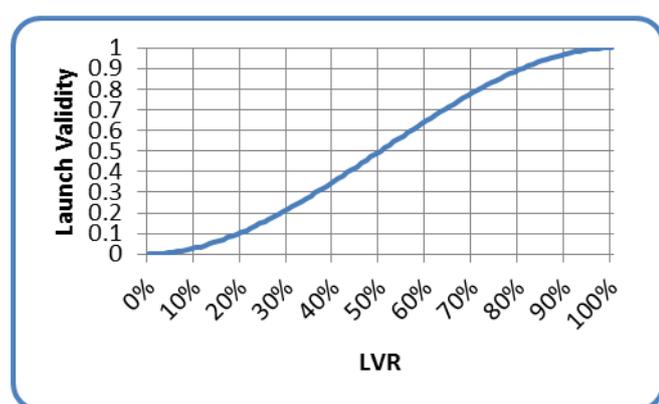


Figure 4: Launch validity curve

9.2 Distance Validity

Distance validity depends on nominal distance, nominal goal, the longest distance flown and the sum of all distances flown beyond minimum distance. If the task distance is quite short in relation to nominal distance, the day is probably not a good measure of pilot skill because there would not be many decisions to make.

If a task is longer than nominal distance, the day will not be devalued because of distance validity, even if the nominal goal parameter value is not achieved, as long as a fair percentage of pilots fly a good distance. This sounds like a vague statement, but the task setter should try to set tasks that are reasonable for the day and achievable. If everyone lands in goal, you must ask if this was a valid test of skill - it probably was if the fastest time and the distance flown were reasonably long. If everyone lands short of goal, was it an unsuitable task but still a good test of pilot skill? You also can have the case where a task that is shorter than nominal distance, has a distance validity of almost 1. This will happen when a large percentage of the pilots fly a large percentage of the course but, in this case, you still have a practical devaluation because there will be little spreading between pilots' scores.

In the formula below, 'p' denotes an individual pilot.

$$SumOfFlownDistancesOverMinDist = \sum_p \max(0, FlownDist_p - MinDist)$$

$$NomDistArea = \frac{((NomGoal + 1) * (NomDist - MinDist)) + \max(0, (NomGoal * (BestDist - NomDist)))}{2}$$

$$DVR = \frac{SumOfFlownDistancesOverMinDist}{NumPilotsFlying * NomDistArea}$$

$$DistanceValidity = \min(1, DVR)$$

9.3 Time Validity

Time validity depends on the fastest time to complete the speed section, in relation to nominal time. If the fastest time to complete the speed section is longer than nominal time, then time validity is always equal to 1.

If the fastest time is quite short, the day is probably not a good measure of pilot skill because there would not be many decisions to make and, because of this, luck can distort scores as there will be little possibility to recover any accidental loss of time.

If no pilot finishes the speed section, then time validity is not based on time but on distance: The distance of the pilot who flies the furthest in relation to nominal distance is then used to calculate the time validity the same way as if it was the time.

$$\text{If one pilot reached ESS: } TVR = \min\left(1, \frac{BestTime}{NominalTime}\right)$$

$$\text{If no pilot reached ESS: } TVR = \min\left(1, \frac{BestDistance}{NominalDistance}\right)$$

$$TimeValidity = \max\left(0, \min\left(1, -0.271 + 2.912 * TVR - 2.098 * TVR^2 + 0.457 * TVR^3\right)\right)$$

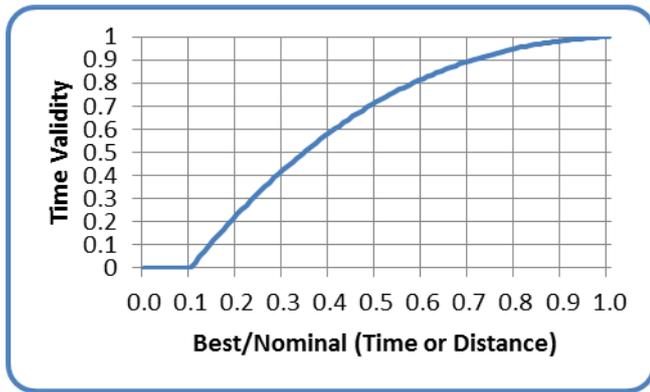


Figure 5: Time validity curve

10 Points Allocation

The available points for each task are 1000*Task Validity. These points are distributed between distance points, time points, leading points and arrival points. The distribution depends on the percentage of pilots who reached goal before the task deadline, compared to pilots who launched, as well as the chosen goal form. It is expressed in terms of weight factors for each of the four point categories: Distance weight, time weight, leading weight and arrival weight. Weight factors are always between 0 and 1. A weight factor of 0.5 for distance, for example, means that 50% of the day's available overall points are available for distance points.

$$GoalRatio = \frac{NumberOfPilotsInGoal}{NumberOfPilotsFlying}$$

$$DistanceWeight = 0.9 - 1.665 * GoalRatio + 1.713 * GoalRatio^2 - 0.587 * GoalRatio^3$$

$$LeadingWeight = \frac{1 - DistanceWeight}{8} * 1.4$$

$$ArrivalWeight = \frac{1 - DistanceWeight}{8}$$

$$ArrivalWeight = 0$$

$$TimeWeight = 1 - DistanceWeight - LeadingWeight - ArrivalWeight$$

$$AvailableDistancePoints = 1000 * TaskValidity * DistanceWeight$$

$$AvailableTimePoints = 1000 * TaskValidity * TimeWeight$$

$$AvailableLeadingPoints = 1000 * TaskValidity * LeadingWeight$$

$$AvailableArrivalPoints = 1000 * TaskValidity * ArrivalWeight$$

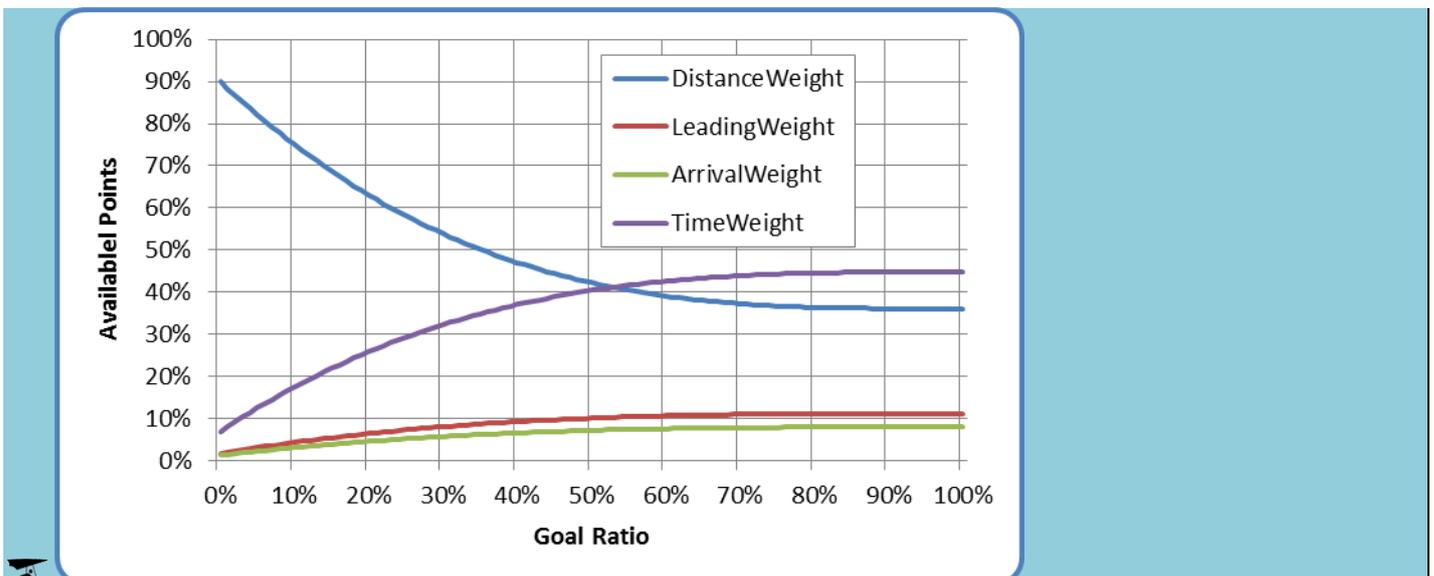


Figure 6: Points allocation curves for hang gliding

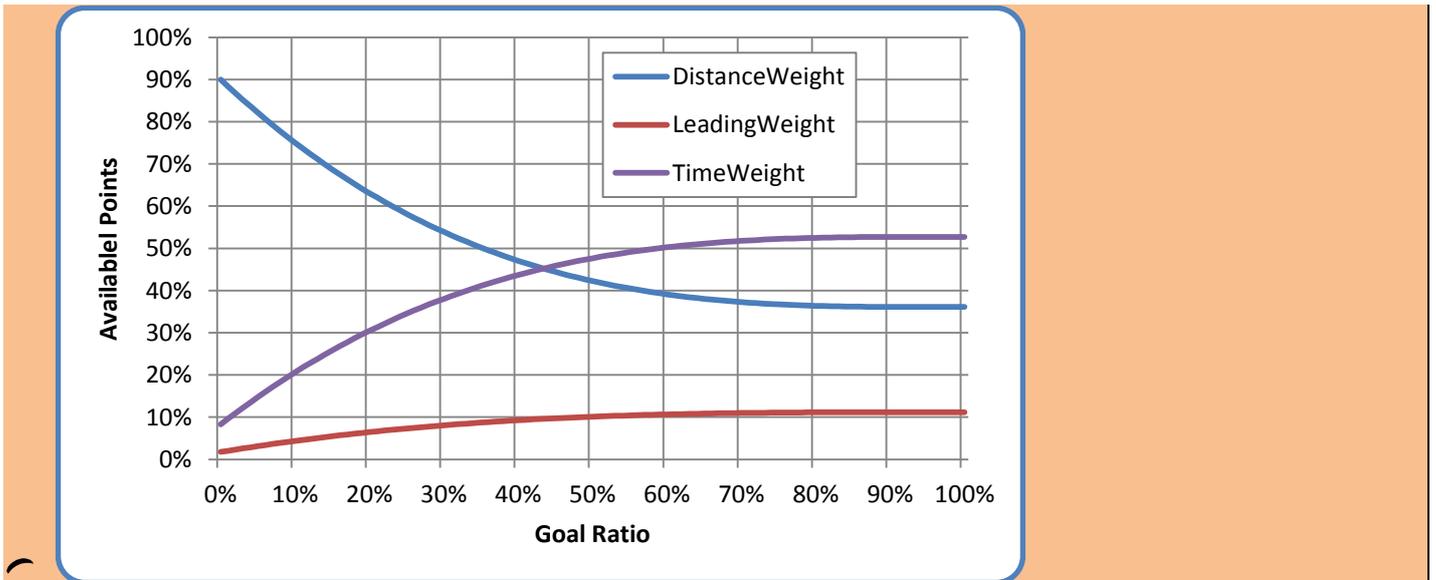


Figure 7: Points allocation curves for paragliding

From the above it follows that if nobody reaches ESS, then a maximum of 900 points are available for distance and 18 points for leading but, of course, no points for time nor arrival. This is also the maximum possible number of points for an open distance task.

$$\text{numberOfPilotsAtESS} = 0 :$$

$$\text{AvailableDistancePoints} = 1000 * \text{TaskValidity} * \text{DistanceWeight}$$

$$\text{AvailableTimePoints} = 0$$

$$\text{AvailableLeadingPoints} = 1000 * \text{TaskValidity} * \text{LeadingWeight}$$

$$\text{AvailableArrivalPoints} = 0$$

$$\text{Max}(\text{AvailableDistancePoints}) = 900$$

$$\text{Max}(\text{availableLeadingPoints}) = 18$$

$$\text{Max}(\text{availableTotalPoints}) = 918$$

11 Pilot score

Each pilot's score is the sum of that pilot's distance, time, leading and arrival points, rounded to the nearest whole number, 0.5 being rounded up.

$$\forall p : p \in \text{PilotsLaunched} : \text{TotalScore}_p = \text{DistancePoints}_p + \text{TimePoints}_p + \text{LeadingPoints}_p + \text{ArrivalPoints}_p$$

11.1 Distance points

The distance considered for each pilot to calculate distance points is that pilot's best distance along the course line, up until the pilot landed or the task deadline was reached, whichever comes first.

✎ One half of the available distance points are assigned to each pilot linearly, based on the pilot's distance flown in relation to the best distance flown in the task. The other half is assigned taking into consideration the difficulty of the kilometers flown.

$$\text{LinearFraction}_p = \frac{\text{Distance}_p}{2 * \text{BestDistance}}$$

$$iDist10_p = \text{int}(\text{Distance}_p * 10)$$

$$\text{DifficultyFraction}_p = \text{DiffScore}_{iDist10_p} + ((\text{DiffScore}_{iDist10_p+1} - \text{DiffScore}_{iDist10_p}) * (\text{Distance}_p * 10 - iDist10_p))$$

$$\text{DistancePoints}_p = (\text{LinearFraction}_p + \text{DifficultyFraction}_p) * \text{AvailableDistancePoints}$$

☞ In the case of a stopped task, a pilot's distance may be increased by an altitude bonus (see 12.3.2). The available distance points are assigned to each pilot linearly, based on the pilot's distance flown in relation to the best distance flown in the task.

$$\text{DistancePoints}_p = \frac{\text{Distance}_p}{\text{BestDistance}} * \text{AvailableDistancePoints}$$

11.1.1 Difficulty calculation

✎ To measure the relative difficulty of each 100 meters of the task, we consider the number of pilots who landed in the successive few kilometers, and the distance flown.

In a first step, for each 100 meter section of the task, the number of pilots who landed in that section is counted. Pilots who landed before minimum distance are counted as having landed at minimum distance. Only pilots who landed out are considered for this calculation, pilots who reached goal are not counted.

$$\forall i : i < \text{int}(\text{MinDist} * 10) : \text{PilotsLanded}_i = 0$$

$$\text{PilotsLanded}_{\text{int}(\text{MinDis} * 10)} = \sum_{\forall \text{Pilot} \text{int}(\text{Pilot.Distance} * 10) \leq \text{int}(\text{MinDis} * 10)} 1$$

$$\forall i : i > \text{int}(\text{MinDist} * 10) \ \& \ i \leq \text{int}(\text{MaxDist} * 10) : \text{PilotsLanded}_i = \sum_{\forall q: q \in \text{PilotsLandedOut} \text{int}(\text{Distance} * 10) = i} 1$$

Then the difficulty for each 100 meter section of the task is calculated by counting the number of pilots who landed further along the task. If 100 pilots land out on a flight of 100 km, the next 3 km are considered. If 10 pilots land out in 100 km, the next 30 km are considered. The variable LookAheadDist contains the number of 100 meter slots to look ahead for this.

$$\text{LookAheadDist} = \max(30, \text{round}(\frac{30 * \text{BestDistanceFlown}}{\text{NumberOfPilotsLandedOut}}, 0))$$

$$\forall i : i \leq \text{int}(\text{MaxDist} * 10) : \text{Difficulty}_i = \sum_{j=i}^{j=\min(i+\text{LookAheadDist}, \text{int}(\text{BestDistanceFlown} * 10))} \text{PilotsLanded}_j$$

$$\text{SumOfDifficulty} = \sum_i \text{Difficulty}_i$$

Relative difficulty is then calculated by dividing each 100 meter slot's difficulty by twice the sum of all difficulty values.

$$\forall i : i \leq \text{int}(\text{MaxDist} * 10) : \text{RelativeDifficulty}_i = \frac{\text{Difficulty}_i}{2 * \text{SumOfDifficulty}}$$

Finally, we can calculate the difficulty score percentage for each 100 meter slot.

$$\forall i : i \leq \text{int}(\text{MinDist} * 10) : \text{DiffScore}_i = \sum_{j=0}^{j=\text{int}(\text{MinDis} * 10)} \text{RelativeDifficulty}_j$$

$$\forall i : i > \text{int}(\text{MinDist} * 10) \ \& \ i < \text{int}(\text{BestDistanceFlown} * 10) : \text{DiffScore}_i = \sum_{j=0}^{j=i} \text{RelativeDifficulty}_j$$

$$\forall i : i \geq \text{int}(\text{BestDistanceFlown} * 10) : \text{DiffScore}_i = 0.5$$

The difficulty calculation does not apply to paragliding.

11.1.1.1 Example for difficulty calculation

For an example of how the difficulty calculation works, see Figure 8: Note how the slope of the green curve (the total Distance points) becomes steeper before an area where many pilots landed and flatter just after. The red circles show these areas before the big group at the 41 km mark, and after the 46 km mark. There are two reasons for this:

1. For safety and retrieval reasons, we do not want to encourage pilots to fly only a short distance past a group of landed pilots.
2. If a pilot lands somewhere, he or she probably got into trouble just before, and then glided a while before landing.

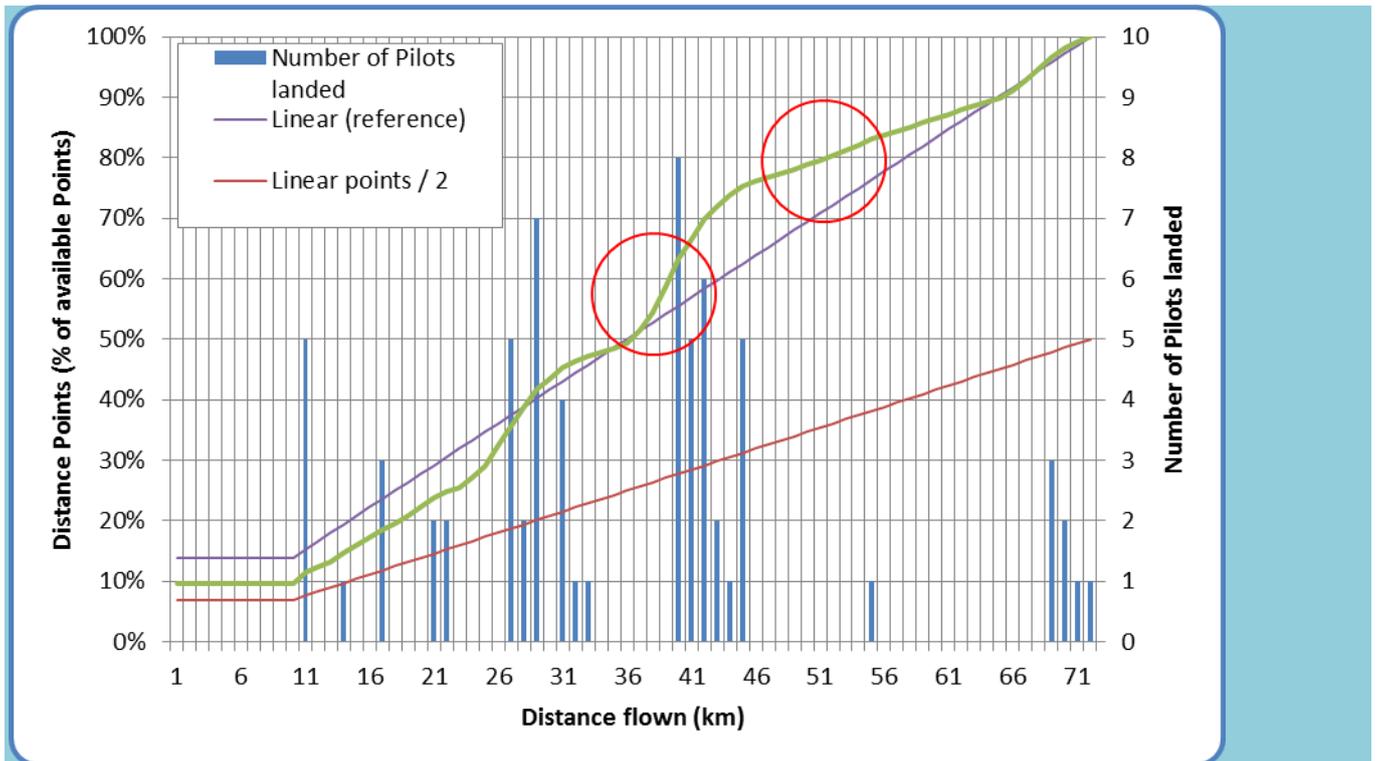


Figure 8: Sample Distance Points

11.2 Time points

Time points are assigned to the pilot as a function of best time and pilot time – the time the pilot took to complete the speed section. Slow pilots will get zero points for speed if their time to complete the speed section is equal to or longer than the fastest time plus the square root of the fastest time. All times are measured in hours.

$$SpeedFraction_p = \max\left(0, 1 - \sqrt[3]{\frac{(Time_p - BestTime)^2}{\sqrt{BestTime}}}\right)$$

$$TimePoints_p = SpeedFraction_p * AvailableTimePoints$$

Examples

For three examples of Time Point distributions for tasks with different best times, see Figure 9 and Table 1.

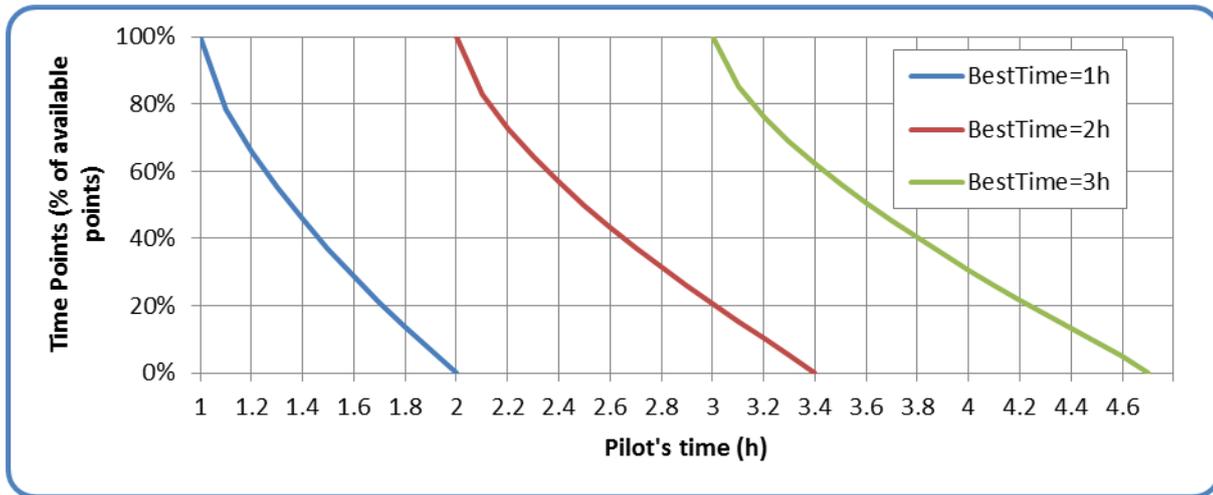


Figure 9: Sample time point distributions

Fastest Time	80% Time Points time	50% Time Points time	0 Time Points time
1:00	1:05	1:21	2:00
2:00	2:08	2:30	3:24 (3.4 hours)
3:00	3:09	3:37	4.42 (4.7 hours)

Table 1: Sample time point distribution (all times in hours:minutes)

11.3 Leading points

Leading points are awarded to encourage pilots to start early and to reward the risk involved in flying in the leading group. Pilots will get leading points even if they landed before goal or the end of speed section.

$$LC_{\min} = \min(\forall p : p \in PilotsFlown : LC_p)$$

$$LeadingFactor_p = \max(0, 1 - \sqrt[3]{\frac{(LC_p - LC_{\min})^2}{\sqrt{LC_{\min}}}}$$

$$LeadingPoints_p = LeadingFactor_p * AvailableLeadingPoints$$

To get an impression of the way leading points are awarded depending on a task's minimal leading coefficient, see Figure 10.

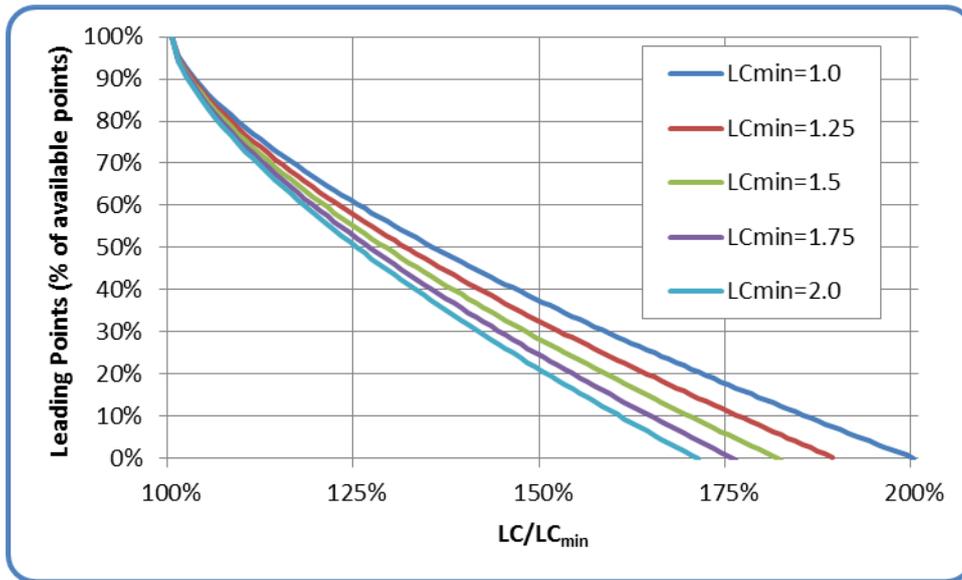


Figure 10: Leading points for various LC_{min}

11.3.1 Leading coefficient

Each started pilot's track log is used to calculate the leading coefficient (LC), by calculating the area underneath a graph defined by each track point's time, and the distance to ESS at that time. The times used for this calculation are given in seconds from the moment when the first pilot crossed SSS, to the time when the last pilot reached ESS. For pilots who land out after the last pilot reached ESS, the calculation keeps going until they land. The distances used for the LC calculation are given in kilometers and are the distance from each point's position to ESS, starting from SSS, but never more than any previously reached distance. This means that the graph never "goes back": even if the pilot flies away from goal for a while, the corresponding points in the graph will use the previously reached best distance towards ESS.

In hang gliding, the original formula for the leading coefficient is used, which is based on the pilot's remaining distance to ESS.

$$LC_p = \frac{\sum_{i: tp_i \in \text{TrackPointsInSS}_p} \text{taskTime}(tp_i) * (\text{bestDistToESS}(tp_{i-1}) - \text{bestDistToESS}(tp_i))}{1800 * \text{LengthOfSpeedSection}}$$

$$\forall p : p \in \text{PilotsLandedOut} \wedge \text{taskTime}(tp_{\max}) < \text{ESSTime}_{\text{LastPilotAESS}} :$$

$$LC_p = LC_p + \text{LastTime}_{\text{LastPilotAESS}} * \text{bestDistToESS}(tp_{\max})$$

$$\forall p : p \in \text{PilotsLandedOut} \wedge \text{taskTime}(tp_{\max}) \geq \text{ESSTime}_{\text{LastPilotAESS}} :$$

$$LC_p = LC_p + \text{taskTime}(tp_{\max}) * \text{bestDistToESS}(tp_{\max})$$

$$\text{taskTime}(tp) = \min(\text{TaskDeadline}, \text{time}(tp))$$

$$\text{bestDistToESS}(tp_0) = \text{LengthOfSpeedSection}$$

$$\forall i : i > 0 \wedge tp_i \in \text{TrackPointsInSS}_p :$$

$$\text{bestDistToESS}(tp_i) = \min(\text{bestDistToESS}(tp_{i-1}), \text{LengthOfSpeedSection} - \text{distanceFlown}(tp_i))$$

Paragliding uses a slightly modified formula for the leading coefficient, where the pilot's remaining distance to ESS is squared. This results more leading points for pilots who fly out front early in the task, compared to the original formula.

$$LC_p = \frac{\sum_{i:tp_i \in \text{TrackPointsInSS}_p} \text{taskTime}(tp_i) * (\text{bestDistToESS}(tp_{i-1})^2 - \text{bestDistToESS}(tp_i)^2)}{1800 * \text{LengthOfSpeedSection}^2}$$

$\forall p : p \in \text{PilotsLandedOut} \wedge \text{taskTime}(tp_{\max}) < \text{ESSTime}_{\text{LastPilotAESS}} :$
 $LC_p = LC_p + \text{LastTime}_{\text{LastPilotAESS}} * \text{bestDistToESS}(tp_{\max})^2$
 $\forall p : p \in \text{PilotsLandedOut} \wedge \text{taskTime}(tp_{\max}) \geq \text{ESSTime}_{\text{LastPilotAESS}} :$
 $LC_p = LC_p + \text{taskTime}(tp_{\max}) * \text{bestDistToESS}(tp_{\max})^2$
 $\text{taskTime}(tp) = \min(\text{TaskDeadline}, \text{time}(tp))$
 $\text{bestDistToESS}(tp_0) = \text{LengthOfSpeedSection}$
 $\forall i : i > 0 \wedge tp_i \in \text{TrackPointsInSS}_p :$
 $\text{bestDistToESS}(tp_i) = \min(\text{bestDistToESS}(tp_{i-1}), \text{LengthOfSpeedSection} - \text{distanceFlown}(tp_i))$

In tasks where CESS is used, the CESS's centre point is considered the last point of the speed section. For LC calculations, any pilot crossing into the CESS's cone is immediately awarded the remaining distance to the cone's centre.

11.3.2 Example

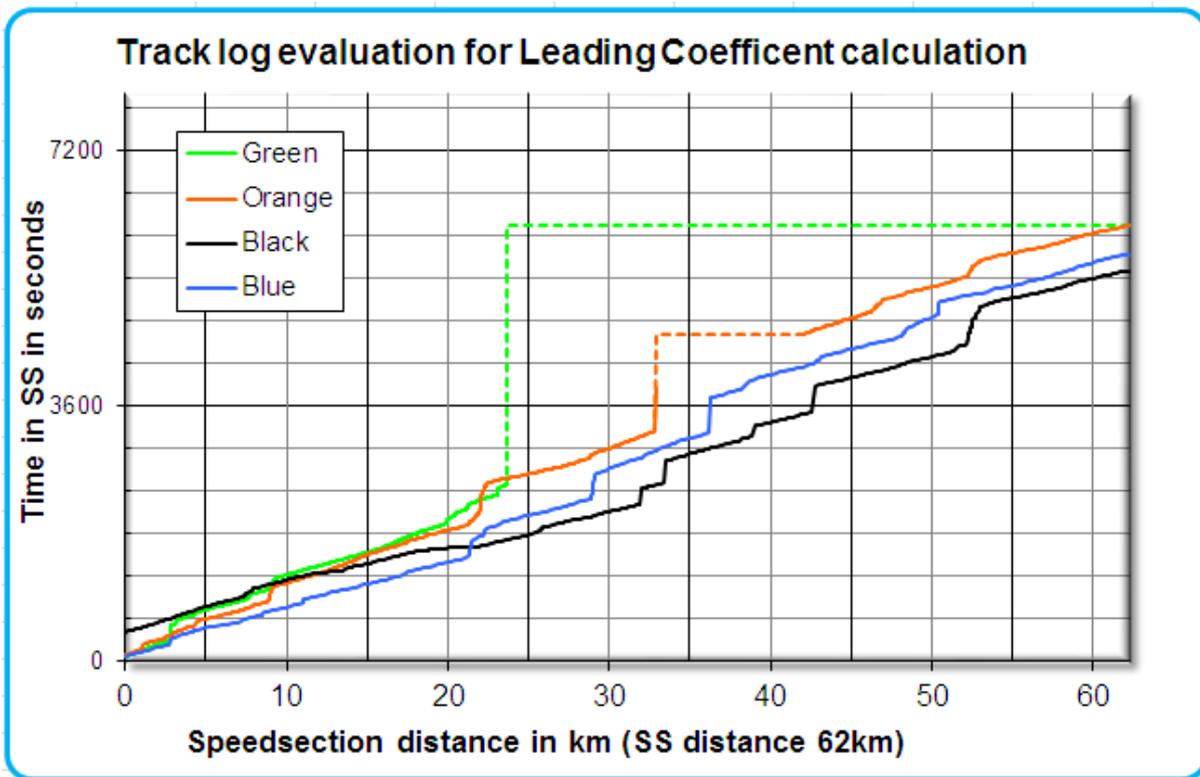


Figure 11: Sample track log graphs for LC calculation

Blue was the first to enter the speed section, but Black was the first pilot to cross the end of speed section. Green started at the same time as Blue, but landed short, after about 23km and just over 40 minutes of flight inside the speed section.

Black was fastest, therefore will get the most time points, but he started late, probably had pilots out front to show the way during the first 22km, but was leading after that.

If a pilot lands along the course (Green), or if his track log is interrupted (Orange), his track log is completed as shown by the dotted lines: Missing parts are calculated as if the dotted line was the actual track log, so LC becomes bigger, lowering the leading points for that pilot, compared to a track where that part is not missing. A pilot landing just short of goal will be less penalised and could even get full leading points if he led for a long while.

The pilot who used best the earliest part of the day (i.e. Black, who has the smallest area below the track log graph) gets all the available leading points, while the others get their points according to the same formula used for the time points for the same reasons. If the task in the example is fully valid, and 30% of pilots reached goal, then Black will get all of the available 81 leading points and full time points, as he was fastest; Blue gets 45 leading points because he started early but was slower; Orange receives only 18 leading points as he was slow and had a gap in his track log; Green gets 0 points even though he started early, because he was the slowest and landed fairly short.

11.4 Arrival points

Arrival points depend on the position at which a pilot crosses ESS: The first pilot completing the speed section receives the maximum available arrival points, while the others are awarded arrival points according to the number of pilots who reached ESS before them. The last pilot to reach ESS will always receive at least 20% of the available arrival points.

$$AC_p = 1 - \frac{\text{PositionAtESS}_p - 1}{\text{NumberOfPilotsReachingESS}}$$

$$\text{ArrivalFraction}_p = 0.2 + 0.037 * AC_p + 0.13 * AC_p^2 + 0.633 * AC_p^3$$

$$\text{ArrivalPoints}_p = \text{ArrivalFraction}_p * \text{AvailableArrivalPoints}$$

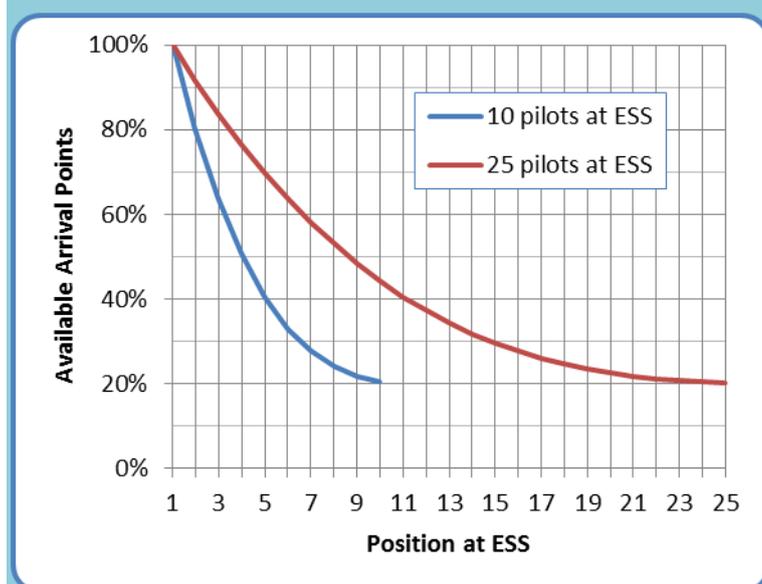


Figure 12: Sample arrival points distributions

No arrival points are awarded in Paragliding.

12 Special cases

12.1 ESS but not goal

In a task where ESS and goal are not identical, a pilot may reach ESS, but not goal. The way this case is handled differs between hang-gliding and paragliding competitions:

In paragliding competitions, reaching goal is seen as “validating” one’s speed section performance. A pilot who does not reach goal after reaching ESS will lose his time points. He will only score distance points for the distance actually covered, and leading points. This is seen as a safety measure, since it encourages pilots to plan their final glide to ESS with enough altitude to safely reach goal. This discourages high-speed final glides low to the ground.

$$\forall p : p \in \text{PilotsLandedBetweenESSandGoal} : \text{TotalScore}_p = \text{DistancePoints}_p + \text{LeadingPoints}_p + 0 * (\text{TimePoints}_p + \text{ArrivalPoints}_p)$$

In hang-gliding competitions, landing between ESS and goal is seen as a slight mishap, which incurs a penalty on the pilot’s total score: Of the time and arrival points scored on the speed section, the pilot will only receive 80%⁷.

$$\forall p : p \in \text{PilotsLandedBetweenESSandGoal} : \text{TotalScore}_p = \text{DistancePoints}_p + \text{LeadingPoints}_p + 0.8 * (\text{TimePoints}_p + \text{ArrivalPoints}_p)$$

12.2 Early start

An early start occurs if a pilot’s last SSS cylinder boundary crossing in start direction (enter or exit) occurred before the first (or only) start gate time.

In paragliding, pilots who perform an early start are only scored for the distance between the launch point and the SSS cylinder, as calculated when determining the complete task distance (see 6.5.1).

In hang-gliding, the so-called “Jump the Gun”-rule applies: If the early start occurred within a time that is close to the first (or only) start gate time, the pilot is scored for his complete flight, but a penalty is then applied to his total score.

The penalty calculation is based on two values X and Y, which are set in S7A, but can be changed at the task briefing (presumably by the meet director and/or the task committee). For each X seconds a pilot starts early, he incurs a 1 point penalty, up to a maximum of Y seconds. If a pilot starts more than Y seconds early, he will only be scored for minimum distance.

⁷ Note that this „rule” is not defined in S7A, but is implemented in FS. Some clarification on the rightfulness of this will be required.

$$X_{default} = 3$$

$$Y_{default} = 300$$

$$timeDiff_p = firstStartGateTime - lastStartTime_p$$

$$timeDiff_p \leq 0 : jumpTheGunPenalty_p = 0$$

$$timeDiff_p > Y : jumpTheGunPenalty_p = 0, totalScore_p = scoreForMinDistance$$

$$0 < timeDiff_p \leq Y : jumpTheGunPenalty_p = \frac{timeDiff_p}{X}$$

$$totalScore_p = \max(totalScore_p - jumpTheGunPenalty_p, scoreForMinDistance)$$

12.3 Stopped tasks

12.3.1 Stop task time

A task can be stopped at any time by the meet director. The time when a stop was announced for the first time is the “task stop announcement time”. This time must be recorded to score the task appropriately. For scoring purposes, a “task stop” time is calculated. This is the time which determines whether a task will be scored at all. Pilots’ flight will only be scored up to this task stop time.

 In hang-gliding, stopped tasks are “scored back” by a time that is determined by the number of start gates and the start gate interval: The task stop time is one start gate interval, or 15 minutes in case of a single start gate, before the task stop announcement time.

$$numberOfStartGates = 1 : taskStopTime = taskStopAnnouncementTime - 15min.$$

$$numberOfStartGates > 1 : taskStopTime = taskStopAnnouncementTime - startGateInterval$$

 In paragliding the score-back time is set as part of the competition parameters (see section 5.7).

$$taskStopTime = taskStopAnnouncementTime - competitionScoreBackTime$$

12.3.2 Requirements to score a stopped task

For a stopped task to be scored, it must fulfil certain requirements, which differ between the two disciplines:

 In hang gliding, a stopped task can only be scored if either a pilot reached goal or the race had been going on for a certain minimum time. The minimum time depends on whether the competition is the Women’s World Championship or not. The race start time is defined as the time when the first valid start was taken by a competition pilot.

$$typeOfCompetition = Women's : minimumTime = 60min.$$

$$typeOfCompetition \neq Women's : minimumTime = 90min.$$

$$taskStopTime - timeOfFirstStart < minimumTime \wedge$$

$$numberOfPilotsInGoal(taskStopTime) = 0 : taskValidity = 0$$

 Note that this rule is currently not enforced by FS: The decision whether a stopped task is cancelled or scored must be taken by the score keeper.

 In paragliding, a stopped task will be scored if the flying time was one hour or more. For Race to Goal tasks, this means that the Task Stop Time must be one hour or more after the race start time. For all

other tasks, in order for them to be scored, the task stop time must be one hour or more after the last pilot started.

$minimumTime = 60 \text{ min} .$

$typeOfTask = RaceToGoal \wedge numberOfStartGates = 1 :$

$taskStopTime - startTime < minimumTime : taskValidity = 0$

$TypeOfTask \neq RaceToGoal \vee numberOfStartGates > 1 :$

$taskStopTime - \max(\forall p : p \in StartedPilots : startTime_p) < minimumTime : taskValidity = 0$

12.3.3 Stopped task validity

For stopped tasks, an additional validity value, the Stopped Task Validity, is calculated and applied to the Task Validity.

$DayQuality_{stopped} = LaunchValidity * DistanceValidity * TimeValidity * StoppedTaskValidity$

Stopped Task Validity is calculated taking into account the task distance, the flown distances of all pilots, the number of launched pilots and the number of pilots still flying at the time when the task was stopped.

$NumberOfPilotsReachedESS > 0 : StoppedTaskValidity = 1$

$NumberOfPilotsReachedESS = 0 :$

$$StoppedTaskValidity = \min\left(1, \sqrt{\frac{BestDistFlown - \text{avg}(\forall i : DistFlown_i)}{DistLaunchToESS - BestDistFlown + 1}} * \sqrt{\frac{\text{stdev}(\forall i : DistFlown_i)}{5}}\right) + \left(\frac{NumPilotsLandedBeforeStopTime}{NumPilotsLaunched}\right)^3$$

12.3.4 Scored time window

For stopped Race to Goal tasks with a single start gate, scoring considers the same time window for all pilots: The time between the race start and the task stop time.

$typeOfTask = RaceToGoal \wedge numberOfStartGates = 1 :$

$\forall p : p \in StartedPilots : scoreTimeWindow_p = (startTime, taskStopTime)$

For stopped Race to Goal tasks with multiple start gates, as well as Elapsed Time races, must be treated slightly differently: Only the time window available to the last pilot started is considered for scoring. This time window is defined as the amount of time t between the last pilot's start and the task stop time. For all pilots, only this time t after their respective start is considered for scoring.

$typeOfTask \neq RaceToGoal \vee numberOfStartGates > 1 :$

$scoreTime = taskStopTime - \max(\forall p : p \in StartedPilots : startTime_p)$

$\forall p : p \in StartedPilots : scoreTimeWindow_p = (startTime_p, startTime_p + scoreTime)$

This means that if the last pilot started and then flew for, for example, 75 minutes until the task was stopped, all tracks are only scored for the first 75 minutes each pilot flew after taking their respective start.

12.3.5 Time points for pilots at or after ESS

Pilots who were at a position between ESS and goal at the task stop time will be scored for their complete flight, including the portion flown after the task stop time. This is to remove any discontinuity between pilots just before goal and pilots who had just reached goal at task stop time.

If a Conical ESS is used, then all pilots who have crossed into the cone before or at the task stop time will be scored for being in goal.

A fixed amount of points is subtracted from the time points of each pilot that makes goal in a stopped task. This amount is the amount of time points a pilot would receive if he had reached ESS exactly at the task stop time. This is to remove any discontinuity between pilots just before ESS and pilots who had just reached ESS at task stop time.

$typeOfTask = RaceToGoal \wedge numberOfStartGates = 1:$

$timePointsReduction = timePoints(taskStopTime - startTime)$

$TypeOfTask \neq RaceToGoal \vee numberOfStartGates > 1:$

$timePointsReduction = timePoints(taskStopTime - \max(\forall p : p \in StartedPilots : startTime_p))$

$\forall p : p \in PilotsInGoal : finalTimePoints_p = timePoints_p - timePointsReduction$

12.3.6 Distance points with altitude bonus

To compensate for altitude differences at the time when a task is stopped, a bonus distance is calculated for each point in the pilots' track logs, based on that point's altitude above goal. This bonus distance is added to the distance achieved at that point. All altitude values used for this calculation are GPS altitude values, as received from the pilots' GPS devices (no compensation for different earth models applied by those devices). For all distance point calculations, including the difficulty calculations in hang-gliding (see 11.1.1), these new stopped distance values are being used to determine the pilots' best distance values. Time and leading point calculations remain the same: they are not affected by the altitude bonus or stopped distance values.

$GlideRatio = 5.0$

$GlideRatio = 4.0$

$\forall p : p \in PilotsLandedBeforeGoal : bestDistance_p = \max(minimumDistance,$

$taskDistance - \min(\forall track_p.point_i :$

$shortestDistanceToGoal(track_p.point_i) - (track_p.point_i.altitude - GoalAltitude) * GlideRatio))$

$\forall p : p \in PilotsReachedGoal : bestDistance_p = taskDistance$

12.4 Penalties

Penalties for various actions are defined in the rules. These penalties are either expressed as an absolute number (e.g. "100 points") or as a percentage (e.g. "10% of the pilot's score in the task where he performed the punishable action"). The corresponding number of points is then deducted from the punished pilot's total score to calculate his final score.

$$finalScore_p = score_p - absolutePenalty_p$$

$$finalScore_p = score_p * (1 - percentagePenalty_p)$$

 These penalties are completely independent of any “Jump the Gun”-Penalty a pilot may have incurred.

The penalty mechanism can also be used to award bonus points to a pilot for some actions like helping a pilot in distress. In that case the penalty must be given as a negative number.

Any rounding up of scores is to be done after the application of penalties. The lowest score a pilot can attain in a task, regardless of any incurred penalties, is zero points.

13 Task ranking

13.1 Overall task ranking

Pilots are ranked by their final score, in descending order. Pilots with the same score are ranked in the same position.

13.2 Female task ranking

A female task ranking is generated by exclusively listing female pilots, with the score they achieved in the overall task ranking. Female pilots with the same score are ranked in the same position.

13.3 Nation task ranking

✈ For the nation task ranking, except for the Women's World Championships, the scores of the three best-ranked pilots of each national team are added up to create each nation's task score. For the nation task ranking at the Women's World Championships, the scores of the two best-ranked pilots of each national team are added up to create each nation's task score. The nations are then ranked by their score, in descending order. Nations with the same score are ranked in the same position.

☪ For the nation task ranking, the scores of the two best-ranked pilots of each national team are added up to create each nation's task score. The nations are then ranked by their score, in descending order. Nations with the same score are ranked in the same position.

14 Competition ranking

14.1 Overall competition ranking

 The competition overall score of a pilot is calculated by adding up all of his task scores. Pilots are then ranked according to their overall total score, in descending order, for the overall competition ranking. Pilots with the same score are ranked in the same position.

 The overall score of a pilot is calculated by using the FTV algorithm described in section 15. For competitions with up to 6 planned tasks, an FTV factor of 0.2 is used. For competitions with 7 or more planned tasks, an FTV factor of 0.25 is used. Pilots are then ranked according to their overall score, in descending order, for the overall competition ranking.⁸

14.2 Female competition ranking

The female competition ranking is generated by exclusively listing female pilots, with the score they achieved in the overall competition ranking.

14.3 Nation competition ranking

The competition score of a nation is calculated by adding up all of that nation's task scores. Nations are then ranked according to their competition total score, in descending order, for the nation competition ranking.

14.4 Ties

If the scores of the first, second or third in the overall, female or nation ranking are identical, the tie shall be broken by adding up the task positions of the tied pilots, or teams. The pilot or team with the lowest sum is declared the winner. If this does not break the tie, joint champions will be declared. For all other ranking positions, pilots or nations with the same score are ranked in the same position.

⁸ Organisers of Category 2 competitions are free to choose whether they want to use FTV for overall scores. Especially for shorter competitions with fewer than 4 tasks, using the traditional method (adding up all task scores for each pilot) may be more suitable.

15 FTV – Fixed Total Validity

Fixed Total Validity (FTV) is a procedure to score pilots on their best task performances, rather than all their tasks. Fixed Total Validity means the sum (total) of available points (validity) is set (fixed) to the same value for each competitor.

$$FTV_factor = 0.2 \vee 0.25$$

$$CalculatedFTV = (1 - FTV_factor) * \sum_{t:Task} \frac{AvailablePoints_t}{1000}$$

To calculate a pilot's FTV score, for all his flights:

1. Calculate a performance percentage for each day by dividing the pilot's day score by the day's available points
2. Arrange all flights in descending order of performance percentage
3. Total up the flights' raw day scores (not performance percentages) in order of performance percentage until the sum of validities for those scores reaches the pre-decided Fixed Total Validity value.

If the last score added takes that pilot's total validity above the Fixed Total Validity, then only a fraction of that score is used so that the pilot's total validity is equal to the Fixed Total Validity.

$$\forall t : t \in ScoredTasks : Performance_{p,t} = \frac{Score_{p,t}}{AvailablePoints_t}$$

$$SortedPerformance_p = \text{sortDescending}(\forall t : t \in ScoredTasks : Performance_{p,t})$$

$$OrderedValidities_p = \text{orderByPerformance}(SortedPerformance_p,$$

$$\forall t : t \in ScoredTasks : \frac{AvailablePoints_t}{1000})$$

$$OrderedScores_p = \text{orderByPerformance}(SortedPerformance_p, \forall t : t \in ScoredTasks : Score_{p,t})$$

$$OrderedScores_{p,u} *$$

$$FTV_Score_p = \sum_{u=0}^{numberOfTasks} \max(1, \frac{\min(0, CalculatedFTV - (u > 0 : \sum_{v=0}^{\min(0,u-1)} OrderedValidities_{p,v}))}{OrderedValidities_{p,u}})$$